AS AD NO. 401717

# A STATISTICAL ROSE PROGRAM

WALTER E. YERGEN

Evaluation Branch
Oceanographic Analysis Division
Marine Sciences Department

**OCTOBER 1962** 





U. S. NAVAL OCEANOGRAPHIC OFFICE WASHINGTON 25, D. C.

# ABSTRACT

This publication describes and evaluates a computer program useful for the statistical processing of bivariate data fields expressed in polar coordinates.

# **FOREWORD**

An IBM 7070 computer program is described. This program is used by the U. S. Naval Oceanographic Office for the statistical processing of bivariate data fields expressed in rose form. The program logic is explained and the quality of the program is evaluated.

Scientific institutions desiring more specific information concerning this program are invited to write to the U.S. Naval Oceanographic Office.

Rear Admiral, U. S. Navy

Commander

U. S. Naval Oceanographic Office

# TABLE OF CONTENTS

																					Page
Foreword				•		•			•	•			•				•	•			iii
Table			•		•	•	•	•	•		•	•		•	•	•	•			•	v
I. Introduction		•		•	•	•	•		•	•		•			•	•	•		•	•	1
II. Program Specifications	•	•		•			•			•	•		٠			•				•	2
III. Program Logic			. •						•												2
IV. Rose Quality Evaluation																					13
Appendix I. Brooks Test Da																					15
Appendix II. Program Test																					16
			7	A.7	В	L	E														
I Frequency Grid Specifics	tio	n s																			17

## A STATISTICAL ROSE PROGRAM

## I. INTRODUCTION

An IBM 7070 computer program is available which will calculate five parameters of frequency distribution over a two dimensional field (the components of the vector mean, the components of standard deviation along the principle axes of the distribution, and the inclination of the major axis), given either raw data, or vector sums and vector sums of squares of data, or processed roses. Having calculated the five parameters of distribution density, the program then integrates frequencies in the polar coordinates of the bivariate, tabulating frequencies for as many as six interval groups in eight cardinal directions, assuming normal distribution.

# The program has several uses:

- 1. It may be used for the statistical processing of any kind of rose, including wind roses, sea and swell roses, current roses, cyclone roses, etc. Program application is not limited to velocity fields. The program may be applied to any bivariate field for which sampling distribution may be normal and elliptical.
- 2. The program may be used for the statistical processing of roses for which data are insufficient to conclude that a rose based on raw data is representative. The program calculates the parameters of distribution density associated with the data rose and produces a statistical rose with the same parameters. Assuming that the data sampling is random and sufficient for calculating representative parameters of distribution and that an infinite random data sampling would yield a normal elliptical frequency distribution field, the statistical rose may be regarded as representative for the rose station. In established study routines, statistical roses have been generated assuming that samples of twenty or more observations per station are adequate to yield representative parameter values but that samples of less than a hundred observations would not be adequate to yield a representative rose using standard methods.
- 3. Under certain circumstances the program may actually be used to calculate statistical roses for places where no data are available. Since the program is designed to calculate a statistical rose from five parameters of distribution density, these five parameters may be fed to the program as data to yield the corresponding statistical

- rose. For an area with scattered stations one may interpolate by analysis procedures the five parameters to be used as data for those places with no data sampling.
- 4. The program may be adjusted to yield arbitrary speed-interval classes for the processed rose. The data rose may thus be processed for speed-interval classes which differ from those given with the rose. If, for example, the speed-interval breakdown of Weather Bureau data differs from a standard speed-interval format, such data may be processed to represent standard speed intervals by employing this program.
- 5. The program may be used to test the assumption graphically that large bivariate data samplings tend toward normalcy of distribution.

## II. PROGRAM SPECIFICATIONS

The program was written in the IBM 70704-tape autocoder language so that maximum use could be made of efficient logic and fixed point arithmetic operations. The program occupies 3572 memory storage addresses at the time of this publication, including the IBM inputoutput subroutine package, and data fields.

The program generally requires twelve to fifteen seconds to process a rose. The frequency integration routine accounts for most of the time required for the production of a rose. Only a few milliseconds are required, in general, for calculating the distribution density parameters of a rose, assuming that the data rose input format is used. Since the machine rents for \$2.50 per minute, machine cost for a single rose ranges between fifty and seventy cents.

Special routines written for the IBM 1401 are used for reading data cards and listing the completed rose.

# III. PROGRAM LOGIC

- A. Calculating the vector mean, vector variance and covariance:
- 1. "Raw" data: Given raw data consisting of two vector components per sample (cartesian or polar coordinates,) a subroutine may be employed which calculates the sum of components, the sum of the squares of components and the sum of component cross-products in the cartesian coordinate system.

Suppose that a raw data format is available which expresses wind data in degrees from north and knots. The subroutine sums and counts successive data samples and calculates the components of the vector mean, vector variance, and covariance according to the formulae:

$$\mathbf{v}_{\mathbf{x}\mathbf{j}} = \mathbf{v}_{\mathbf{j}} \sin \theta_{\mathbf{j}} \tag{1}$$

$$v_{yj} = v_{j} \cos \theta_{j} \tag{2}$$

$$\bar{\mathbf{v}}_{\mathbf{x}} = \frac{1}{N} \sum_{\mathbf{x}, \mathbf{i}} \mathbf{v}_{\mathbf{x}, \mathbf{i}} \tag{3}$$

$$\bar{\mathbf{v}}_{\mathbf{y}} = \frac{1}{N} \sum_{\mathbf{y}j} \mathbf{v}_{\mathbf{y}j} \tag{4}$$

$$S_x^2 = \frac{1}{N} \sum_{xj}^{v_{xj}^2} - \bar{v}_x^2$$
 (5)

$$s_y^2 = \frac{1}{N} \sum_{y_j}^{v_{j}^2} - \bar{v}_y^2$$
 (6)

$$cov = \frac{1}{N} \sum_{xj} v_{xj} v_{yj} - \bar{v}_{x} \bar{v}_{y}$$
 (7)

where

N: Total frequency of observations

j: The jth data sample

 $\theta_{j}$ : Degrees from north of the jth data sample

v;: speed (knots) of the jth data sample

x: The east-west coordinate axis

y: The north-south coordinate axis

 $v_x$ : The X-component of the vector mean

v: The Y-component of the vector mean

S<sub>x</sub><sup>2</sup>: The X-component of the vector variance

S<sub>v</sub><sup>2</sup>: The Y-component of the vector variance

cov: The covariance of the X-Y components

2. Data rose: Given a data rose, wherein raw data has previously been tabulated in specified speed-interval classes for the eight cardinal directions; the vector mean, vector variance and covariance may be calculated using the formulae:

where i: the ith speed group in

d: the dth direction class

a; the midpoint speed in the ith speed group

Fid: the frequency of observations in the (i-d)th

speed-direction group

Because the centroid of distribution in a speed-direction group is not generally coincident with the point of intersection of the group midpoint speed and the ray bisecting the octal direction class, this method of calculating distribution parameters may not yield wholly accurate results. This method characteristically exaggerates the distribution spread, for instance, producing an overestimate for the scalar mean velocity and the vector variance. Functions may be applied which will approximately correct for the interval errors intrinsic in this method; however, the program does not presently incorporate these correction functions.

B. Calculating the inclination of the principle axes of the distribution and the components of standard deviation along the principle axes of the distribution: The equations used for calculating the parameters of the distribution were derived from equations provided in "An Introduction to the Theory of Statistics."\*

Let 
$$K_1 = S_x^2 + S_y^2$$
 (11)

$$K_2 = S_x^2 - S_y^2$$
 (12)

$$L = (K_2^2 + 4\cos^2)^{\frac{1}{2}}$$
 (13)

then 
$$E_1 = \left[0.5(K_1 + L)\right]^{\frac{1}{2}}$$
 (14)

$$E_2 = (K_1 - E_1^2)^{\frac{1}{2}} \tag{15}$$

<sup>\*</sup> G. U. Yule and M. G. Kendall, "An Introduction to the Theory of Statistics," Edition 13; Charles Griffin & Company, Limited; London, 1949, chapter 12, pp. 227-232.

Where E<sub>1</sub>: The component of standard deviation along the major axis of the distribution

E<sub>2</sub>: The component of standard deviation along the minor axis of the distribution

Let 0' represent the angle included between the X-coordinate and one of the principal axes of the distribution. Then

$$tan 20^{\circ} = 2cov / K_2$$

$$0^{\circ} = 0.5 \arctan (2cov / K_2)$$
(16)

If  $K_2 > 0$ , let  $\theta = \theta^0$ ; otherwise let  $\theta = \theta^0 + 90^\circ$ . If  $K_2 = 0$ , then if  $\cos < 0$ ,  $\theta = -45^\circ$ ; otherwise  $\theta = +45^\circ$ . Then  $\theta$  identifies the major axis of the distribution.

- C. Integrating frequencies for the normal surface within the limits of specified direction and speed classes
- 1. General description of the method of integration: The program regards the normal surface as a grid of 2,228 areas of known frequency. The grid is uniquely defined by the parameters of distribution density. The program locates the centroid of each such area in the polar coordinates of the bivariate and accordingly tabulates the known frequency in the appropriate speed-direction group.
- 2. Assumptions employed in deriving the grid of areas of known frequency: The normal surface may be visualized as a bell shaped mound with elliptical horizontal cross-sections, its axis of symmetry representing the ordinate which measures density of distribution frequency and perpendicular to the plane which measures vector variates. The equation for distribution density (the normal surface) is given\* for a point (x,y) in cartesian coordinates coincident with the principal axes of the distribution:

$$\sigma_{x,y} = \frac{e^{-\frac{1}{2}\left[\left(x/E_1\right)^2 + \left(y/E_2\right)^2\right]}}{2\pi E_1 E_2}$$
(17.a)

or

<sup>\*</sup> Yule and Kendall, op. cit.

The exponent in equation (17.a) is elliptical in form. Let a cross-section of the distribution be identified with the parameter,  $\downarrow$ , such that

$$\frac{x^2}{E_1^2} + \frac{y^2}{E_2^2} = \chi^2 \tag{18.a}$$

The parameter  $\{$  identifies an ellipse which intersects the major axis of the distribution at the point  $E_1\}$  and the minor axis at the point  $E_2\}$ .  $\}$ , then, is a factor of proportionality relating elliptical crosssections of the distribution, and is everywhere constant along the perimeter of an ellipse. It follows from equation (17.a) that the density of distribution is likewise constant at each point along the perimeter of an elliptical cross-section, and that it may be given:

$$\sigma \chi = \frac{e^{-\frac{1}{2}\chi^2}}{2\pi E_1 E_2} \tag{17.b}$$

Let the polar coordinates  $(R,\emptyset)$  be defined such that  $\frac{X}{R} = \cos \theta$ ;  $\frac{Y}{R} = \sin \theta$ . Then  $x = R\cos \theta$ ;  $y = R \sin \theta$ , and the ellipse, equation (18.a) may be expressed in the polar coordinates  $(R,\emptyset)$ :

$$R^{2} = E_{1}^{2} E_{2}^{2} \chi^{2} / (E_{2}^{2} \cos^{2} \theta + E_{1}^{2} \sin^{2} \theta) = E^{2} \chi^{2}$$
 (18.b)

and 
$$x = \mathbb{E} \nmid \cos \theta$$
,  $y = \mathbb{E} \nmid \sin \theta$ 

The frequency of distribution is given for a segment:

$$\mathbf{F}_{\mathbf{x},\mathbf{y}} = \int_{\mathbf{x}} \mathbf{x} \int_{\mathbf{x}} \sigma_{\mathbf{x},\mathbf{y}} \, d\mathbf{x} \, d\mathbf{y}$$
 (19.a)

It is convenient to integrate equation (19.a) between ellipses. Then the integral (19.a) may be transformed to the elliptical coordinates,  $(\ \ \ \ \ \ )$ :

$$F_{\chi,\emptyset} = \int_{\chi} \int \sigma_{\chi} J\begin{pmatrix} x & y \\ \lambda & \emptyset \end{pmatrix} d\lambda d\emptyset$$
 (19.b)

where the Jacobian, 
$$J\begin{pmatrix} x & y \\ \lambda & \emptyset \end{pmatrix} = \frac{\partial x}{\partial \lambda} \frac{\partial y}{\partial \emptyset} - \frac{\partial x}{\partial \emptyset} \frac{\partial y}{\partial \lambda} = \mathbb{E}^2 \lambda$$
 (20)

so that 
$$F_{\chi,\emptyset} = \int_{\emptyset} \int_{\mathbb{R}} \sigma_{\chi} \mathbb{E}^2 \chi d\chi d\emptyset$$
 (19.c)

Since  $\mbox{$\chi$}$  and  $\mbox{$\emptyset$}$  are mutually independent, functions involving  $\mbox{$\chi$}$  only may be extracted from equation (19.c) as constants with respect to  $\mbox{$\emptyset$}$ , and conversely. Then, integrating between the limits  $\mbox{$\chi$}_1$  and  $\mbox{$\chi$}_2$ ,  $\mbox{$\emptyset$}_1$  and  $\mbox{$\emptyset$}_2$ :

$$F_{\chi,\emptyset} = \frac{1}{\pi E_1 E_2} \left[ \chi_1^{\chi_2} e^{-\frac{1}{2} \chi^2} \chi_d \chi \right] \left[ \int_{0}^{0} \frac{1}{2} E^2 d\theta \right]$$
(21)

$$= \frac{1}{2^{\frac{1}{W}}} \left( e^{-\frac{1}{2} \left( \frac{1}{1} \right)^2} - e^{-\frac{1}{2} \left( \frac{2}{1} \right)} \right) \left[ \operatorname{arctan} \left( \frac{E_1}{E_2} \tan \theta_2 \right) - \operatorname{arctan} \left( \frac{E_1}{E_2} \tan \theta_1 \right) \right]$$
(22)

Evaluating equation (22) between the limits  $(\cline{1} = 0, \cline{1} = 2\pi)$  and  $(\cline{1} = 0, \cline{1} = 2\pi)$  provides the frequency of distribution enclosed by the ellipse  $\cline{1}$ :

$$F(x) = 1 - e^{-\frac{1}{2}x^2}$$
 (23)

Conversely, given the frequency of distribution, F, enclosed by an ellipse, to identify the parameter of the ellipse:

$$\langle = \left[ -2 \ln(1 - F) \right]^{\frac{1}{2}}$$
(24)

It may be noted that the  $\emptyset$  integral in equation (21) provides the area of the sector of the unit ellipse which is subtended by the angle  $(\emptyset_2 - \emptyset_1)$ . The  $\xi$  integral provides the frequency of distribution between the ellipses  $\xi_1$  and  $\xi_2$ . The equation (21) therefore shows that sectors

including equal areas of the unit ellipse likewise include equal frequencies of the distribution in the ring between adjacent ellipses. The normal elliptical distribution may therefore be subdivided into segments of known frequency, employing a grid of sectors subtending equal areas of the unit ellipse and ellipses enclosing known frequencies of the distribution.

The grid of sectors of equal area may be derived by employing an arbitrary parametric angle,  $\psi$ , such that points on the unit ellipse may be given in cartesian coordinates coincident with the principal axes of the distribution:

$$\tilde{P} = (E_1 \cos \psi, E_2 \sin \psi) \tag{25}$$
accordingly, 
$$\tan \theta = \frac{E_2}{E_1} \tan \psi$$

so that the area of the sector defined by \(\psi\) is given:

$$A = \frac{E_1 E_2}{2} \arctan \left( \frac{E_1}{E_2} \tan \theta \right) = \frac{E_1 E_2}{2} \psi$$

and integer multiples of the parametric angle  $\psi$  shall define integer multiples of the unit sector area defined by  $\psi$ .

Given the grid of segments of known frequency, it is required to find a representative point in each segment such that if the segment overlaps adjacent speed-direction groups the point shall be tallied in the group containing the greatest portion of the segment frequency. The centroid of the segment may be regarded as the desired representative point. The coordinates of the centroid of a segment may be determined, in cartesian coordinates, (x,y), coincident with the principal axes of the distribution:

$$\bar{x} = \frac{\sqrt{\int x} x \sigma_{x,y} dx dy}{\sqrt{\int x} \int \sigma_{x,y} dx dy}$$

$$\bar{y} = \frac{\sqrt{\int x} y \sigma_{x,y} dx dy}{\sqrt{\int x} \int \sigma_{x,y} dx dy}$$
(26)

Since  $x = E_1 \nmid \cos \psi$ ,  $y = E_2 \nmid \sin \psi$  the equations (26) may be transformed to the elliptical coordinates,  $( \nmid, \psi )$ :

$$\lambda_{x} = \frac{\psi \int_{\lambda} \int E_{1} \lambda \cos \psi \, \sigma_{\lambda} J(x, y) \, d\lambda \, d\psi}{\psi \int_{\lambda} \int \sigma_{\lambda} J(x, y) \, d\lambda \, d\psi}$$

$$= \frac{E_{1} \psi \int_{\lambda} \int \sigma_{\lambda} \lambda^{2} \cos \psi \, d\lambda \, d\psi}{\psi \int_{\lambda} \int \sigma_{\lambda} \lambda \, d\lambda \, d\psi}$$

$$= E_{1} \frac{H(\lambda)}{F(\lambda)} \lambda \frac{\psi \int \cos \psi \, d\psi}{\psi \int d\psi}$$

$$\psi \int d\psi$$
where  $H(\lambda) = \lambda^{2} \int_{\lambda} \int e^{-\frac{1}{2}\lambda^{2}} \lambda^{2} \, d\lambda, \quad F(\lambda) = \lambda^{2} \int_{\lambda} \int e^{-\frac{1}{2}\lambda^{2}} \lambda \, d\lambda$ 

Likewise,  $\begin{cases} \chi = E_2 & \frac{H(\lambda)}{F(\lambda)} \end{cases} \qquad \frac{\psi^{\int \sin \psi \, d\psi}}{\psi^{\int d\psi}}$  (28)

 $F(\ell)$ , evaluated between ellipses  $\ell_{j-1}$  and  $\ell_j$  provides the frequency of distribution between the two ellipses. The function,  $H(\ell)$ , may be evaluated between the same limits:

$$H(\chi) = \chi_{j-1} = \chi_{j-1} = \chi_{j-1} = \frac{\int \chi_j}{2} \chi^2 d\chi = \sum_{n=0}^{\infty} \frac{(-1)^n (\chi_j^{2n+3} - \chi_{j-1}^{2n+3})}{2^n (2n+3) n!}$$
(29)

Let  $(n-\frac{1}{2})\psi$ , define successive rays including sectors of equal areas in the unit ellipse for n=0, 1, 2, etc. Then integrating the equations (27) and (28) between the limits  $(\chi_{j-1})$ ,  $(\chi_j)$  and  $(n-\frac{1}{2})\psi$ ,  $(n+\frac{1}{2})\psi$  provides the components,  $\overline{P}_{j,n}$ , of the centroid of the corresponding segment:

$$\overline{P}_{j,n} = \frac{1}{\psi} \frac{H(\frac{1}{2})}{F(\frac{1}{2})} \bigg|_{\frac{1}{2} = 1} \bigg\{ E_1 \left[ \sin(n + \frac{1}{2})\psi - \sin(n - \frac{1}{2})\psi \right] E_2 \left[ \cos(n - \frac{1}{2})\psi - \cos(n + \frac{1}{2})\psi \right] \bigg\}$$

$$= (E_{1} \overline{X}_{j} \cos n\psi, \quad E_{2} \overline{X}_{j} \sin n\psi)$$

$$\text{where } \overline{X}_{j} = \frac{H(\overline{X})}{F(\overline{X})} \Big]_{j=1}^{X_{j}} \quad G(\psi), \text{ and } G(\psi) = \frac{2 \sin \frac{1}{2} \psi}{\psi}$$

$$(30)$$

That is, the ray defined by  $n \psi$  bisects the area of the sector defined between the rays  $(n-\frac{1}{2}) \psi$  and  $(n+\frac{1}{2}) \psi$ , and so bisects the frequency of distribution included in the sector. It may be noted that when n = 0,  $\overline{P}_{j,0}$  is proportional to the module,  $E_1$ , of the major axis. When  $n \psi = 90^{\circ}$ ,  $\overline{P}_{j,n}$  is proportional to the module,  $E_2$  of the minor axis. The locus of  $\overline{P}_{j,n}$ , for j,  $\psi$  constants, is an ellipse.

The function,  $G(\psi)$  is the factor providing correction for sector parallax. It may be noted that as the parametric angle,  $\psi$ , approaches the limit, 0,  $G(\psi)$  approaches the limit, 1, so that the sector parallax error vanishes as the sector angle vanishes.

The parameters  $\{i\}$  and  $n \neq thus$  define the grid of segment centroids, and may be predetermined. The equation (30) relates the grid to the individual rose operated upon by the program. Grid choice is arbitrary. Grid segments were defined for this program so as to enclose discrete values of distribution frequency. The corresponding  $\{i\}$  values were then calculated employing equations (25), for given n-intervals, and (24). The grid was chosen for segment definition such that segment areas would be of comparable magnitude and of similar shape, and such that maximum programming advantage could be taken of grid symmetry. The grid specifications are presented in table I.

3. Locating the segment of known frequency in the grid of direction-speed interval classes: The equation (30) expresses the point,  $R_{j_an}$ , in cartesian coordinates coincident with the principal axes of the distribution, and is transformed to components in the coordinate system of the bivariate with the equations:

$$X_{j,n} = (E_1 \cos \theta) (\bar{X}_j \cos n\psi) - (E_2 \sin \theta) (\bar{X}_j \sin n\psi) + \bar{v}_x$$

$$Y_{j,n} = (E_2 \cos \theta) (\bar{X}_j \sin n\psi) + (E_1 \sin \theta) (\bar{X}_j \cos n\psi) + \bar{v}_y$$
(31)

The point is located within the limits,  $V_1$  and  $V_2$ , of a designated speed interval class if

$$V_1^2 \le (X_{j,n}^2 + Y_{j,n}^2) < V_2^2$$

The point is located within the appropriate octal direction class according to the following logic:

(1) If 
$$|X_{j,n}| \tan 22\frac{1}{2}^{\circ} > |Y_{j,n}|$$
, then: (a) if  $X_{j,n} > 0$ , EAST

(b) otherwise, WEST

(2) If 
$$\left| Y_{j,n} \right| \tan 22 \frac{1}{2} > \left| X_{j,n} \right|$$
, then: (a) if  $Y_{j,n} > 0$ , NORTH

(b) otherwise, SOUTH

(3) Otherwise, if 
$$X_{j,n} > 0$$
, then: (a) if  $Y_{j,n} > 0$ , NORTHEAST

(b) otherwise, SOUTHEAST

(4) Otherwise, 
$$X_{j,n} < 0$$
, then: (a) if  $Y_{j,n} > 0$ , NORTHWEST

(b) otherwise, SOUTHWEST

#### IV. ROSE QUALITY EVALUATION

It was not practical to hand-calculate a rose for control results after the manner employed by the program. Hand-calculation of a single rose would have required several months to perform, and would at best have provided a check against the arithmetic of the program rather than a check against fundamental program logic. Rather, test data known or assumed to be normally distributed were processed by the program and the results were examined for correspondence with the test data.

## A. Brooks' circular normal rose data

Brooks'\* roses supplied from tables were used as one source of test data. These roses are theoretically characterized by normal-circular distribution and are useful for testing the program logic, equation (30), for the special case,  $E_1 = E_2$ . The table roses, however, are derived by graphical interpolation methods, and may not be exactly normal nor circular in fact. A representative test sample is provided in appendix I. The Brooks' data rose is listed along with the components of the vector and scalar means which theoretically identify it. The program image of the data rose is listed for easy comparison.

#### B. Program roses as test data

Theoretically, the program supplies roses which are elliptically and normally distributed. Consequently the program rose supplies data ideal for a test against itself. A representative sample test is provided in appendix II.

C. Analysis of test results: This test provides an index of rose degeneration due both to the method of rose frequency integration and to the method (Section III.A.2) for calculating the parameters of the data rose. The method of rose frequency integration may be expected to produce distortions in the image rose because of segment area overlap between adjacent speed-direction groups. However, the frequency tabulation error due to the overlapping of a segment between adjacent speed-direction groups may be either positive or negative for a group, and the collection of such errors tend in general to cancel

<sup>\*</sup>Brooks and Carruthers, "Handbook of Statistical Methods in Meteorology," M. O. 538. London, Her Majesty's Stationery Office, 1953; Chapter 11.

as the frequency population of the group is tallied. The method of frequency integration therefore probably does not account for consistent divergences between the data rose and its program image. Distortions due to this method may be likened to a "white noise" which is diminished in intensity as the frequency grid is divided into smaller and smaller segments. The method (Section III.A.2), on the other hand, may be expected to produce image rose values for the scalar mean and vector deviations,  $E_1$  and  $E_2$ , which consistently exceed the corresponding values for the data rose.

In appendix I it may be noted that  $E_1$  and  $E_2$  are only approximately equivalent. This may be taken to indicate either that the object rose does not represent an exactly circular distribution or that the method for calculating the parameters of the data rose may thus distort the relationship between these parameters. The more probable alternative is that the object rose does not represent an exactly circular distribution; in appendix II, wherein a program rose is compared with its own image, it may be noted that the inclination of the major axis and the ratio of deviations between the principal axes closely coincide.

The distortion due to the method of calculating parameters of the data rose is, however, apparent in both the Brooks' and program rose samples; that is, the program image values for the scalar mean velocity and the vector deviations exceed the corresponding parameters for the test rose. Nevertheless, corresponding values between the test roses and their program images are clearly similar, particularly for the program rose. Such similarity suggests that the program logic is successful, and that rose distortion due to segment overlap error is small. Unfortunately, the precise extent of segment overlap error is masked by the distortion which may be attributed to the method for calculating data rose parameters. The error introduced by the program method for frequency integration cannot be estimated with any precision from these test results.

D. Conclusion: The program can probably be improved by applying an interval correction function to the method (Section III.A.2) for calculating the parameters of a data rose. Doubtless, too, there is a more efficient method for integrating frequencies of the distribution in the speed-direction interval classes. However, test samples suggest that the program rose is of substantial quality, and that the program may be employed confidently whenever program application is warranted.

Appendix I: BROCKS TEST DATA ROSE

Speed groups: I, 00 -10; II, 10 - 20; III, 20 - 20; (kmets) IV, 40 -60; V, 60 - 100; VI, 200+

	·			<b>-</b>	-	-	Print No. 1: 2 recomme
	Test	program			Tost	program	
	roso	image	diff		rese	image	<b>d11</b> 2
	24 OF	20 00					
roan	26.95	29.00	2.05	SI	1.10	1.03	.02
Vx	-19.10	-19.5k	.hh	II	2.80	2.92	.12
Vy	- 6.60	- 6.50	10	III	5.20	5.56	.36
ente	•	99625		IA	1.20	1.59	-39
E1	40	18.04	•	A	0	.14	.14
E2	9	16.85		IV	0	0	C
	deta	*****	1440			* * *	
N I	.80	.84	.04	SW I	1,40	1.38	.02
" II	1.40	1.52	.12	II	5.50	5.07	.43
TTI	1.50	1.77	.28	III	17.90	15.67	2.23
IV	.30	.29	.01	IV	6,60	7.35	.75
v	ō	o o	Û	ੂੰ ਪ੍ਰ	.60	.95	.35
VI	ð	0	C	77	0	0	o
		* * 8	-			* * *	
nr I	.50	-61	.11	¥ X	1.40	1.38	02ء
II	.80	.76	.OÅ	<b></b> 5	5.90	5 <b>.35</b>	. 55 655
III	.50	• 75 • 53	(0)	24 777	19.30		1.88
īv	0	•9. <del>.</del>	0	TA .	7.00	7.58	.58
Ā	ő	Õ	Ğ	, v	.60	.93	.99 .99
VI	6	0	0	AI.	.00	0	رر. 0
٧.	•	* * *	C	<b>₹</b> &	43	* * *	•
						_	
<u>r</u> I	.50	.56	.06	w I	1.20	1.14	06ء
II	.70	.78	.08	II	3.30	3.24	.06
III	.ko	<b>.</b> 45	.05	III	7.00	7.38	82.
IV	0	0	0	IA	L - 30	2.95	.55
¥	0	0	0	Å	.10	.21	.11
VI	0	0	0	VI	0	0	O
		****			<b>全书</b> 000		and the same of th
SE I	.70	.65	.05	Total I	7.60	7.6	್ಯಂಪಿ
II	1.20	1.22	.02	II	21.60	20.85	. 74
III	1.60	1.18	.18	III	52.80	89.95	2.04
1A	.10	.14	.0b	IV	17.00	19.31	2.31
V	C	0	0	V	1.30	2.29	, 99 39
<b>YI</b>	0	O	0	VI	0	6	9

<sup>\*</sup> The angle & is in the fourth quadrant

Appendix II: PROGRAM TEST DATA ROSE

Speed groups: I, 00 - 10; II, 10 - 20; III, 20 - 40; (kmots) IV, 40 - 60; V, 60 - 100; VI, 100+

	Test	program			Test	program	
	rese	image	1110		TOSO	1.me.go	alle
mean.	29.07	30,18	1.11	<u>s</u> I	، <del>78</del>	. 66	.12
Vz	-14.71	-14.77	.05	II	1.39	1.49	.10
٧y	10.49	10.52	.03	III	1.61	1.80	.19
sine	.73534 <sup>*</sup>	•79973*	.00439	IV	.24	.39	.09
<b>B1</b>	20.16	21.30	1.14	A	0	0	0
<b>B</b> 2	18.29	19.38	1.09	TV	0	0	0
B1/B2	1.102	1.099	.003			* * *	
	****	****	<b>神</b> 李李				
N I	1.20	1.08	.12	<u>sv</u> i	1.08	1.08	0
II	3.60	3.24	•36	II	2.58	2.40	.18
III	9.15	8.93	.22	III	5.21	5.38	-17
IA	3.80	b.21	.41	IV	1.70	2. <del>3</del> 9	• <b>3</b> 9
A	.52	.74	. 22	V	. 20	.9h	.14
VI	0	Ö	0	VI	O	0	0
		* * *				* * *	
NR I	•96	.90	.06	¥ I	1.26	1.08	.18
II	2.07	2.04	.03	TI	4.92	3.96	.96
III	3.42	3.54	.12	III	12.12	11.46	.66
Y	.86	1.16	.30	IV	5.95	5.18	.23
V	.07	.14	.07	v	.99	1.3b	.42
VI	0	0	0	VI	0	0	0
		* * *				* * *	
R I	.72	.72	0	W I	1.38	1.32	.06
TI T	1.18	1.26	.08	11	4.88	4.47	.41
III	1.08	1.94	.26	III	14.88	13.55	1.33
IA	.15	.18	.03	IV	7.07	7.21	.14
V	0	0	0	v	1.09	1.57	.48
VI	0	0	0	VI	o o	0	G
		* * *		•		******	***
se i	.78	.72	.06	TOTAL I	8.16	7.56	.60
II	•97	1.05	.08	II	20.99	19.91	1.03
III	.71	.94	.23	III	48.18	46.94	1.24
IV	.10	.11	.01	īv	19.87	21.41	1.54
V	0	0	0	<b>V</b>	2.80	4.18	1.38
VI	0	0	0	VI	O	0	0
		* * *				¢ េះ 🕏	

<sup>\*</sup> Both angles are in the first quadrant

TABLE 1: FREQUENCY GRID SPECIFICATIONS

المجتن	-/2/20	0°038767	0.081634	0.120626	0.163830	0.211092	0.272543	0.338560	0.394539	0.44442 0.10010	0.490185	0,532870	0.573244	0.011/01 0.011/01	0.657257	0.737597	0.804667	0°86600	0.993773	9.717.66.0	1,0605/51	1.124518	1.169250	1.255586	1.360003	1.51034k	1,666961	1.637037	2,003517	2.109500	2000 C	300000	\$ 100 mm	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	9°26082°6
$H({\mathcal X}_j)$	0.000060		44444444444444444444444444444444444444	20000000000000000000000000000000000000	7022000	0,0042&7			0.000000000000000000000000000000000000	0.004450	DOCT-000	6201000	0.002033	14000 C	0.100245	0,128580	0.159891	0.192905	0.228776	0.267089	0.307825	0.951020	0.396706	० क्ष्मिक्ष	0.549401	0.665407	0.772103	0.889685	0.96667	1.072847	1,109978	SON SE		20 Call 20 Cal	1.253314
ټ	0.056595	0.104060	128960	0.189kgc	1 4 4 4 5 C	1404CZ-0	ALBOYS O	0 100000	O. MARCHA	0.512780	O. KKAPRA	Agrada O	0.631550			0.01/1050	0.837827	0°902293	0,965908	1.029241	1.092804	1.157092	1.222614	1.289922	1,432554	1.592023	1.746490	1,93567	2.078983	2.326393	2,438039	2 207469	00000000000000000000000000000000000000	2457746	8
COM FREQ in straight in the st	910	32.	3	7.7	2.73	77	, K	24 ×	10,40	12.32	18.28	16.16	18,08	21.02	36 36 36 36	07.00	3.63	\$ \$ . N. N.	37.28	41.12	64.90	000000	52° <b>6</b> 2	56.20	64.16	71.64	76,24	<b>5.</b>	86 <del>1</del> 8	92.32	88.48	67.73	65.43	2.5	30.00
cum num of segments	7	12	20	*	, r	18	116	148	180	212	244	276	308	372	74	200	3 4	ŔS	920	2 7 7	8	0 4 0 4 0 4	항 ( 항 교 항 (	3	1076	1204	1332	9 <del>5</del> 7	1586	1716	18481	1972	0017	) (S) (S) (S) (S) (S) (S) (S) (S) (S) (S	2440
FREQ (%) ring 3-1,1	91°	24.	9	8	8	1.92	1.92	1.92	1,92	1.92	1.92	1.92	1.92	3.0	3.8	2 84	ā	) e	400	\$ 6 6 6	2000	\$ 6 N	# 60° N		99°2	200%	0.40	07.9	## (F	<b>3</b>	2.56	2.56	(4)	000	) } 4
FREQ (%) Per sogment	₹.	ŝ	કુ	ŝ	8	90.	8.	૪	8	8.	ۍ. وو	8	8.	ક્	ઠુ	80°	ò	. S	3	ŝ	8	3 8	8 8	\$ %	9 2	3	j.	ş, (	ž, (	5	889	, 0,	50.	92.5 \$4.5	:
num of segments ring 3-1,5	*	œ	<b>6</b> 0	<b>1</b> 6	16	32	32	32	32	32	32	91	32	₹	49	179	ব্য	3	3	ব	179	ব	3	200		128	0 6	9 6	000	9 0	240	N N	120	() (;)	
sector engle,	8.	in a	r. R	22.5	22.5	11.25	11,25	11,25	11,25	11.25	11.25	-	11.25	•	5.625	5.625	5.625	5.623	5.625	5.625			1 60 S	2.8125	2.8128	2.8124		100	7012		0 01 9E	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	in i		
Ellipse number.	est 1	L;	<b>ሮ</b> ነ.	辟	ĸ	v	~	ග	<b>6</b> \	10	1	2	ମ ୴	珍	15	<b>1</b>	~	89 80	19	20	21	22	23								-			ઝર	

U. S. Naval Oceanographic Office	A STATISTICAL ROSE PROGRAM, by Walter E.	Yergen. October 1962, 21 p., including appendixes	and table. (SP-64).
U. S. Nav	A ST	Yergen.	and table.

This special publication describes and evaluates a computer program useful for the statistical processing of bivariate data fields.

1. Normal bivariate surface

3. Computer programs 2. Data processing

5. Oceanography 4. Climatology

i, title: A Statistical Rose Program ii. Author: Walter E. Yergen

iii. SP-64

and table. (SP-64).

U. S. Naval Oceanographic Office A STATISTICAL ROSE PROGRAM, by Walter E. Yergen. October 1962, 21 p., including appendixes

This special publication describes and evaluates a computer program useful for the statistical processing of bivariate data fields.

5. Oceanography

 Normal bivariate surface
 Data processing
 Computer programs A STATISTICAL ROSE PROGRAM, by Walter E. U. S. Naval Oceanographic Office

Yergen, October 1962. 21 p., including appendixes

4. Climatology

5. Oceanography

i. title: A Statistical Rose Program ii. Author: Walter E. Yergen

> i, title; A Statit Cal Rose Program ii. Author: Walter E. Yergen

This special publication describes and evaluates a computer program useful for the statistical proc-

cesing of bivariate data fields.

iii. SP-64

This special publication describes and evaluates a computer program useful for the statistical processing of bivariate data fields.

and table, (SP-64).

1. Normal bivariate surface

3. Computer programs

4. Climatology 5. Oceanography

2. Data processing

U. S. Naval Oceanographic Office
A STATISTICAL ROSE PROGRAM, by Walter E. Yergen. October 1962. 21 p., including appendixes

and table, (SP-64),

1. Normal bivariate surface

.

これのない場合は最初の関係の国際の対象を対象を持ちないのできませんが、対象を対象を対象を対象をある。 かいまたがい あんかい しょうかい しゅうしゅうしゅうしゅう

2. Data processing 3. Computer programs 4. Climatology i, title: A Statistical Rose Program ii. Author: Walter E. Yergen iii. SP-64